



Quick Start Guide

Unidrive M100-101

Frame sizes 1 to 4

Value drive with quality and performance for open loop applications

Part Number: 0478-0035-06

Issue: 6

This guide is intended to provide basic information required in order to set-up a drive to run a motor. For more detailed installation information, please refer to the *Unidrive M100 / 101 User Guide* which is available to download from:

<http://www.emersonindustrial.com/en-EN/controltechniques/downloads/userguidesandsoftware/Pages/downloads.aspx>.

or
www.emersonindustrial.com/en-EN/leroy-somer-motors-drives/downloads/Pages/manuals.aspx.

Warnings, Cautions and Notes



A Warning contains information which is essential for avoiding a safety hazard.



A Caution contains information which is necessary for avoiding a risk of damage to the product or other equipment.

NOTE

A **Note** contains information, which helps to ensure correct operation of the product.



This guide does not include safety information. Incorrect installation or operation of the drive, could cause personnel injury or equipment damage. For essential safety information, please refer to the *Unidrive M100 / 101 User Guide* or the safety booklet supplied with the drive.

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Declaration of Conformity

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This declaration applies to the Unidrive-M product range comprising model numbers listed below:

Model No.	Interpretation	Format: Xaaa-bbc ddddde	Format: Xaa-bbc ddddde
X	Application	M = Manufacturing Automation, E = Elevator, F = Flow, H = HVAC, CSD = Compressor	HS = High Speed
aa(a)	Control System	100, 101, 200, 201, 300, 400, 600, 700, 701, 702	70, 71, 72
bb	Frame Size	01, 02, 03, 04, 05, 06, 07, 08, 09, 10, 11	
c	Voltage Rating	1 = 100 V, 2 = 200 V, 4 = 400 V, 5 = 575 V, 6 = 690 V	
dddd	Current Rating	Example 01000 = 100 A	
e	Configuration	A = AC in AC out (with internal choke), D = DC in AC out (Inverter), C = AC in DC out (Rectifier), E = AC in AC out (without internal choke), T = AC in AC out with Dual Rectifier	

The model number may be followed by additional characters that do not affect the ratings.

The variable speed drive products listed above have been designed and manufactured in accordance with the following European harmonized standards:

EN 61800-5-1:2007	Adjustable speed electrical power drive systems - Part 5-1: Safety requirements - Electrical, thermal and energy
EN 61800-3: 2004	Adjustable speed electrical power drive systems - Part 3: EMC requirements and specific test methods
EN 61000-6-2:2005	Electromagnetic compatibility (EMC) - Part 6-2: Generic standards - Immunity for industrial environments
EN 61000-6-4:2007	Electromagnetic compatibility (EMC) - Part 6-4: Generic standards - Emission standard for industrial environments
EN 61000-3-2:2006	Electromagnetic compatibility (EMC) - Part 3-2: Limits for harmonic current emissions (equipment input current ≤16 A per phase)
EN 61000-3-3:2008	Electromagnetic compatibility (EMC) - Part 3-3: Limitation of voltage changes, voltage fluctuations and flicker in public, low voltage supply systems, for equipment with rated current ≤16 A per phase and not subject to conditional connection

EN 61000-3-2: 2006 Applicable where input current < 16 A. No limits apply for professional equipment where input power ≥1 kW.

These products comply with the Restriction of Hazardous Substances Directive - RoHS 2011/65/EU, the Low Voltage Directive - LVD 2006/95/EC and the Electromagnetic Compatibility Directive - EMC 2004/108/EC.



G. Williams
Vice President, Technology
Date: 30th July 2015
Place: Newtown, Powys, UK

These electronic drive products are intended to be used with appropriate motors, controllers, electrical protection components and other equipment to form complete end products or systems. Compliance with safety and EMC regulations depends upon installing and configuring drives correctly, including using the specified input filters. The drives must be installed only by professional installers who are familiar with requirements for safety and EMC. The assembler is responsible for ensuring that the end product or system complies with all the relevant laws in the country where it is to be used. Refer to the User Guide. An EMC data sheet is also available giving detailed EMC information.

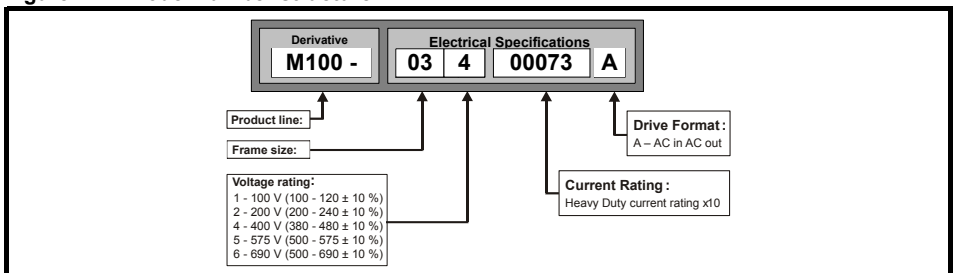
1 Product information

1.1 Ratings

Model	Input phases ph	Max. cont input current A	Max input fuse rating		Nominal cable size				Output current		
			1 Ph A	3 Ph A	European		USA		Max. cont output current A	Nominal power kW	Motor power hp
					Input mm ²	Output mm ²	Input AWG	Output AWG			
01100017	1	8.7	10		1	1	16	16	1.7	0.25	0.33
01100024	1	11.1	16		1	1	14	16	2.4	0.37	0.5
01200017	1	4.5	6		1	1	16	16	1.7	0.25	0.33
01200024	1	5.3	6		1	1	16	16	2.4	0.37	0.5
01200033	1	8.3	10		1	1	16	16	3.3	0.55	0.75
01200042	1	10.4	16		1	1	16	16	4.2	0.75	1
02100042	1	18.8	20		2.5	1	12	16	4.2	0.75	1
02100056	1	24	25		4	1	10	16	5.6	1.1	1.5
02200024	1 / 3	5.3/4.1	6	6	1	1	16	16	2.4	0.37	0.5
02200033	1 / 3	8.3/6.7	10	10	1	1	16	16	3.3	0.55	0.75
02200042	1 / 3	10.4/7.5	16	10	1	1	16	16	4.2	0.75	1
02200056	1 / 3	14.9/11.3	20	15	2.5/1.5	1	12/14	16	5.6	1.1	1.5
02200075	1 / 3	18.1/13.5	20	15	2.5	1	12	16	7.5	1.5	2
02400013	3	2.4		6	1	1	16	16	1.3	0.37	0.5
02400018	3	2.9		6	1	1	16	16	1.8	0.55	0.75
02400023	3	3.5		6	1	1	16	16	2.3	0.75	1
02400032	3	5.1		6	1	1	16	16	3.2	1.1	1.5
02400041	3	6.2		10	1	1	16	16	4.1	1.5	2
03200100	1 / 3	23.9/17.7	25	20	4	1.5	10/12	14	10	2.2	3
03400056	3	8.7		10	1	1	14	16	5.6	2.2	3
03400073	3	12.2		16	1.5	1	12	16	7.3	3	3
03400094	3	14.8		16	2.5	1.5	12	14	9.4	4	5
04200133	1 / 3	23.7/16.9	25	20	4/2.5	2.5	10	12	13.3	3	3
04200176	3	21.3		25	4	2.5	10	12	17.6	4	5
04400135	3	16.3		20	2.5	2.5	10	12	13.5	5.5	7.5
04400170	3	20.7		25	4	2.5	10	12	17	7.5	10


NOTE The nominal cable sizes shown in the table above, are provided as a guide only. Ensure that the cables used conform to the local wiring regulations.

Figure 1-1 Model number structure



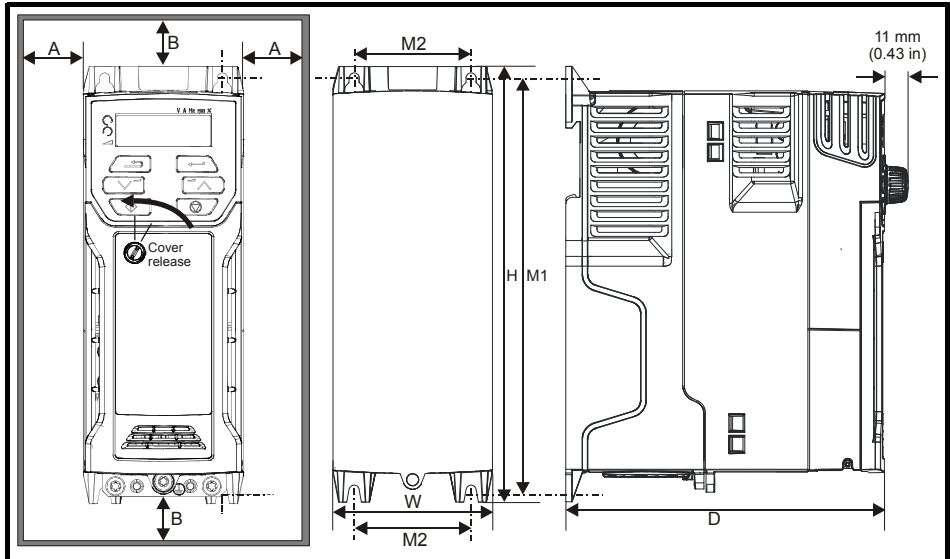
2 Options

Table 2-1 AI Backup adaptor

Type	Option module	Name	Further Details
Backup		AI-Smart Adaptor	See <i>Drive User Guide</i>
		AI-Backup Adaptor	

3 Mechanical installation

The drives can be panel mounted with 0 mm space between the drives. For further information on mechanical installation refer to the *Drive User Guide*.



To remove the terminal cover, use a flat bladed screwdriver to rotate the terminal cover locating clip by approximately 30° in a counter clockwise direction, and then slide the cover down.

Drive Size	H		W		D		M1		M2		Ø		A		B*	
	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in
1	160	6.30	75	2.95	130	5.12	143	5.70	53	2.08	5	0.2	0	0.00	100	3.93
2	205	8.07	78	3.07	150	5.91	194	7.63	55	2.17	5	0.2				
3	226	8.90	90	3.54	160	6.30	215	8.46	70.7	2.80	5	0.2				
4	277	10.91	115	4.53	175	6.89	265	10.43	86	3.40	6	0.23				

NOTE A minimum clearance of 100 mm above and below Frame 01 to 04 products is required for applications where the product is subjected to rated load and rated ambient temperature.

NOTE * A minimum clearance of 50 mm above and below Frame 01 to 04 products is permissible in applications where either the ambient operating temperature is 35 °C or less or the average output current is derated by 20 %.

NOTE Derating for reduced clearances is to be applied in addition to the derating for increased switching frequency if operating above 3 kHz. Refer to the *Drive User Guide* for the current derating due to an increase in switching frequency.

NOTE If Din rail mounting is used in an installation, then mounting screws should be used to secure the drive to the back plate.

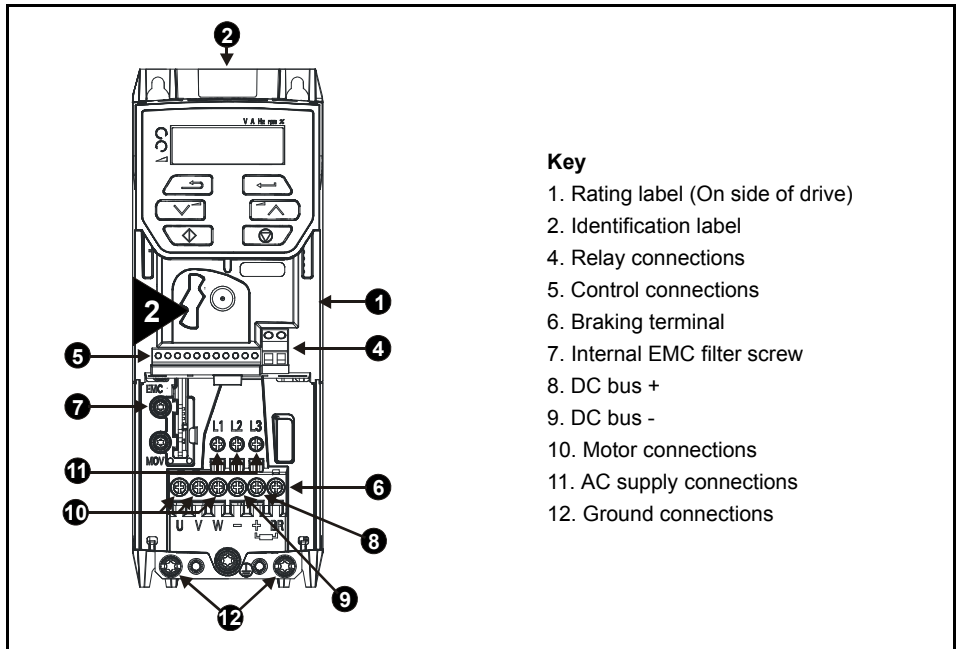
Table 3-1 Tools required

Tool	Location	Size 1	Size 2	Size 3	Size 4
Small terminal screwdriver	Control, relay terminals	✓	✓	✓	✓
3 mm Flat-bladed screwdriver	Power terminals	✓			
5 mm Flat-bladed screwdriver	Terminal cover	✓	✓	✓	✓
4 mm Flat-bladed screwdriver	AC power terminals		✓		
Philips screwdriver	Power terminals		✓	✓	✓
Torx 10 driver	EMC & MOV screws	✓	✓	✓	✓
Torx 15 driver	Fan screw	✓			
Torx 20 driver	Fan screw		✓	✓	✓

Table 3-2 Recommended torque settings

Model size	Terminal block description	Torque settings
All	Control terminals	0.2 N m (0.15 lb ft)
	Relay terminals	0.5 N m (0.37 lb ft)
1	Power terminals	0.5 N m (0.37 lb ft)
2, 3, 4		1.4 N m (1.03 lb ft)

Figure 3-1 Feature diagram (size 2 shown)



4 Electrical installation

An overlay of the electrical connections / terminals is included on the back page of this manual.

4.1 AC supply requirements

Voltage:

100 V drive: 100 V to 120 V \pm 10 %

200 V drive: 200 V to 240 V \pm 10 %

400 V drive: 380 V to 480 V \pm 10 %

Number of phases: 3

Maximum supply imbalance: 2 % negative phase sequence (equivalent to 3 % voltage imbalance between phases).

Frequency range: 48 to 62 Hz

For UL compliance only, the maximum supply symmetrical fault current must be limited to 100 kA.

NOTE On the size 2 110 V drives or when connecting single phase to a dual rated 200 V unit, the supply should be connected to L1 and L3. Also the DC bus (-) terminal on 110 V drives has no internal connection. The 110 V drives use a voltage doubler circuit on the input, therefore the default for *Motor Rated Voltage* (00.008) is 230 V.

4.2 External braking resistor



Overload protection

When an external braking resistor is used, it is essential that an overload protection device is incorporated in the braking resistor circuit; as shown in the electrical diagram on the back cover.

4.2.1 Minimum resistance values and peak power rating for the braking resistor at 40 °C (104 °F)

Table 4-1 Braking resistor resistance and power rating (100 V)

Model	Minimum resistance* Ω	Instantaneous power rating kW	Continuous power rating kW
01100017	130	1.2	0.25
01100024			0.37
02100042	68	2.2	0.75
02100056			1.1

Table 4-2 Braking resistor resistance and power rating (200 V)

Model	Minimum resistance* Ω	Instantaneous power rating kW	Continuous power rating kW
01200017	130	1.2	0.25
01200024			0.37
01200033			0.55
01200042			0.75
02200024	68	2.2	0.37
02200033			0.55
02200042			0.75
02200056			1.1
02200075			1.5
03200100	45	3.4	2.2
04200133	22	6.9	3.0
04200176			4.0

Table 4-3 Braking resistor resistance and power rating (400 V)

Model	Minimum resistance* Ω	Instantaneous power rating kW	Continuous power rating kW
02400013	270	2.3	0.37
02400018			0.55
02400023			0.75
02400032			1.1
02400041			1.5
03400056	100	6.1	2.2
03400073			3
03400094			4
04400135	50	12.2	5.5
04400170			7.5

* Resistor tolerance: ±10 %

4.3 Ground leakage

The ground leakage current depends upon whether the internal EMC filter is installed or not. The drive is supplied with the filter installed. Instructions for removing the internal filter are given in section 4.5.1 *Internal EMC filter* on page 17.

With internal filter installed:

Size 1:

- 2.5 mA* AC at 230 V 50 Hz (line to line supply, star point ground)
- 9.2 mA* AC at 230 V 50 Hz (line to neutral supply, star point ground)

Size 2:

- 9.36 mA* AC at 110 V, 50 Hz (2 phase, line to line supply, star point ground)
- 16.4 mA* AC at 110 V, 50 Hz (1 phase, line to neutral supply, star point ground)
- 5.3 mA* AC at 230 V, 50 Hz (3 phase supply, star point ground)
- 15.4 mA* AC at 230 V, 50 Hz (1 phase, line to neutral supply, star point ground)
- 9.6 mA* AC at 400 V, 50 Hz (3 phase supply, star point ground)

Size 3:

- 19.7 mA* AC at 400 V 50 Hz (star point ground)
- 47.4 mA* AC at 400 V 50 Hz (corner ground)

Size 4:

- 21 mA* AC at 230 V 50 Hz (3 phase, star point ground)
- 6.8 mA* AC at 230 V 50 Hz (1 phase, line to line supply, star point ground)
- 30 mA* AC at 230 V 50 Hz (1 phase, line to neutral supply, star point ground)
- 50 mA* AC at 400 V 50 Hz (3 phase, star point ground)

*Proportional to the supply voltage and frequency.

With internal filter removed:

Size 1: <1.5 mA (line to line supply, star point ground)

<1 mA (line to neutral supply, star point ground)

Size 2: <1.7 mA (line to line supply, star point ground)

<1.9 mA (line to neutral supply, star point ground)

Size 3: <3.3 mA (star point ground)

<4.9 mA (corner ground)

Size 4: < 3.5 mA (star point ground)

NOTE

The above leakage currents are just the leakage currents of the drive with the internal EMC filter connected and do not take into account any leakage currents of the motor or motor cable.



When the internal filter is installed the leakage current is high. In this case a permanent fixed ground connection must be provided, or other suitable measures taken to prevent a safety hazard occurring if the connection is lost.



When the leakage current exceeds 3.5 mA, a permanent fixed ground connection must be provided using two independent conductors each with a cross-section equal to or exceeding that of the supply conductors. The drive is provided with two ground connections to facilitate this. Both ground connections are necessary to meet EN 61800-5-1: 2007.

4.3.1 Use of residual current device (RCD)

There are three common types of ELCB / RCD:

1. AC - detects AC fault currents
2. A - detects AC and pulsating DC fault currents (provided the DC current reaches zero at least once every half cycle)
3. B - detects AC, pulsating DC and smooth DC fault currents
 - Type AC should never be used with drives.
 - Type A can only be used with single phase drives
 - Type B must be used with three phase drives



Only type B ELCB / RCD are suitable for use with 3 phase inverter drives.

If an external EMC filter is used, a delay of at least 50 ms should be incorporated to ensure spurious trips are not seen. The leakage current is likely to exceed the trip level if all of the phases are not energized simultaneously.

4.4 Control terminal configurations and wiring

00.005		Drive Configuration								
RW	Txt						PT	US		
OL	↕	AV (0), AI (1), AV.Pr (2), AI.Pr (3), Preset (4), Pad (5), Pad.Ref (6), torque (8)				⇒	AV (0)*			

* With Unidrive M101, the default is Pad (5).

Value	Text	Description
0	AV	Analog input 1 (voltage)
1	AI	Analog input 1 (current)
2	AV.Pr	Analog input 1 (voltage) or 3 presets selected by terminal
3	AI.Pr	Analog input 1 (current) or 3 presets selected by terminal
4	Preset	Four presets selected by terminal
5	Pad	Keypad reference
6	Pad.Ref	Keypad reference with terminal control
8	torque	Torque mode, Analog input 1 (voltage torque reference) selected by terminal

This parameter is used to automatically setup the user programmable area in the advanced parameter set according to drive configurations. Other default values may also be changed by drive configuration. Parameters are stored in EEPROM automatically following a configuration change. Defaults are loaded before drive configuration changes are made. Defaults loaded are defined by *Defaults Previously Loaded*.

Action will only occur if the drive is inactive, not in UU state and no User Actions are running. Otherwise, the parameter will return to its pre altered value on exit from edit mode. All parameters are saved if this parameter changes.

Figure 4-1 Pr 00.005 = AV (50 Hz)

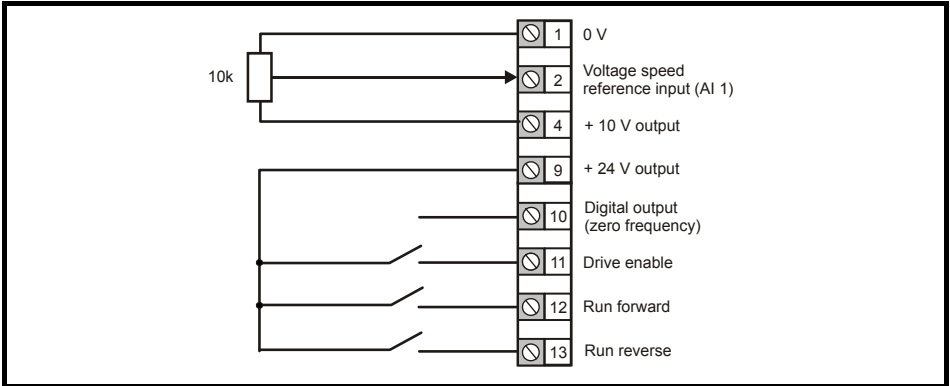


Figure 4-2 Pr 00.005 = AV (60 Hz)

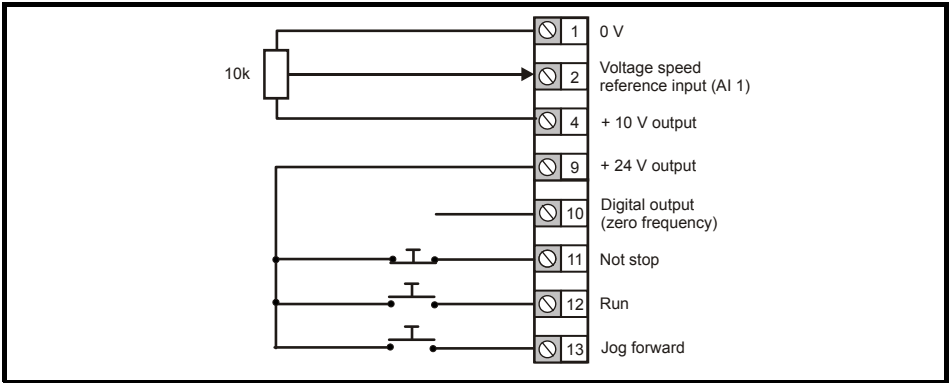


Figure 4-3 Pr 00.005 = AI (50 Hz)

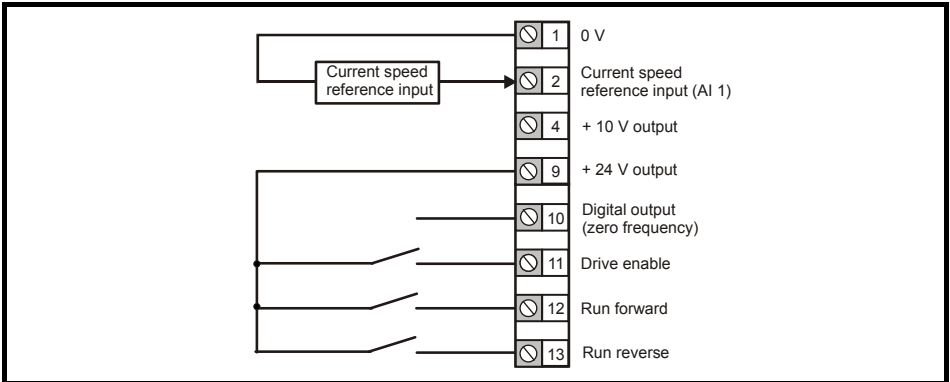


Figure 4-4 Pr 00.005 = AI (60 Hz)

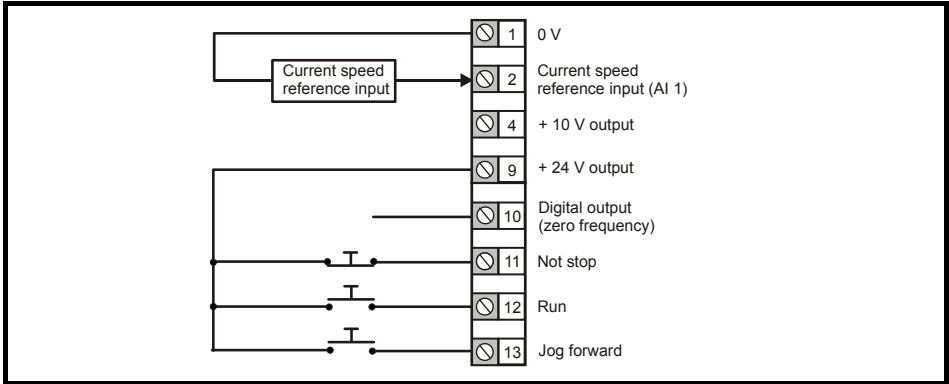


Figure 4-5 Pr 00.005 = AV.Pr (50 Hz)

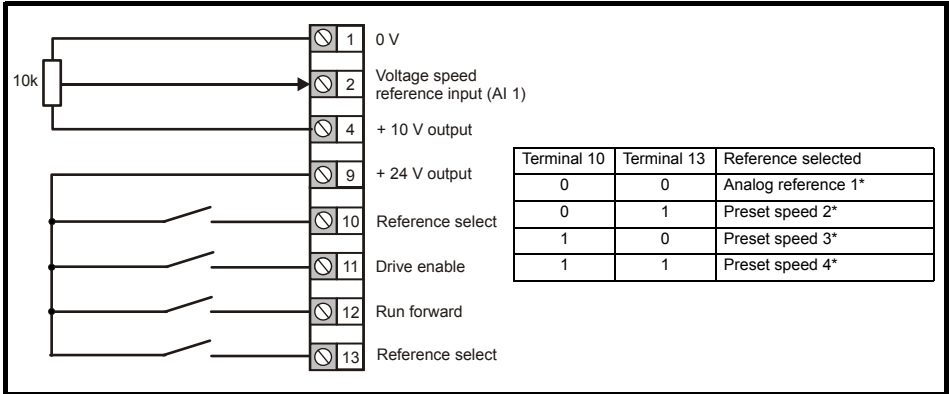
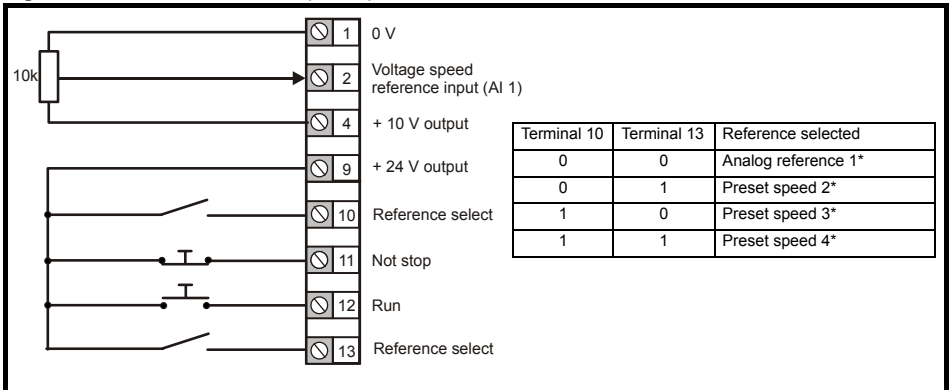


Figure 4-6 Pr 00.005 = AV.Pr (60 Hz)



* Refer to *Drive User Guide*.

Figure 4-7 Pr 00.005 = AI.Pr (50 Hz)

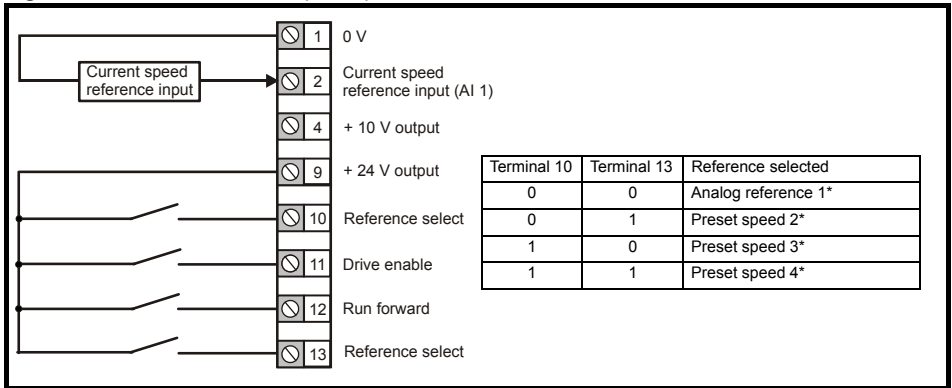


Figure 4-8 Pr 00.005 = AI.Pr (60 Hz)

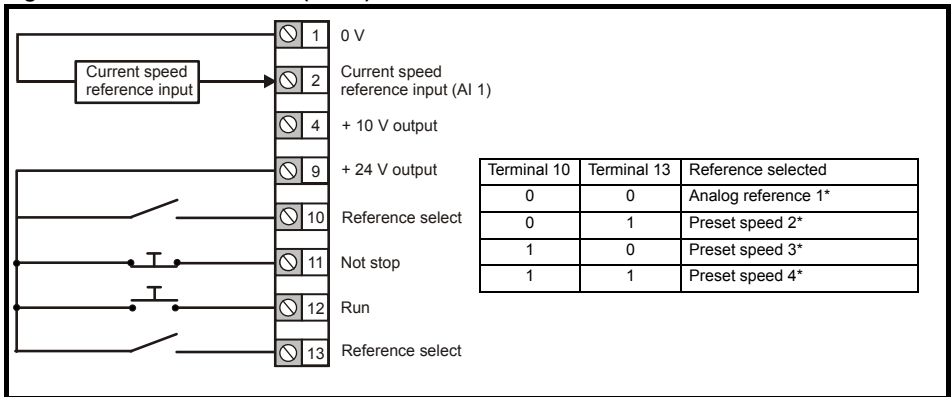
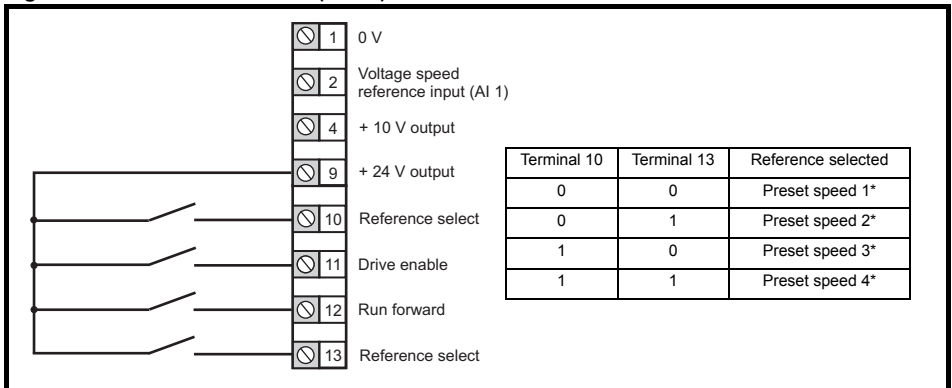


Figure 4-9 Pr 00.005 = Preset (50 Hz)



* Refer to *Drive User Guide*.

Figure 4-10 Pr 00.005 = Preset (60 Hz)

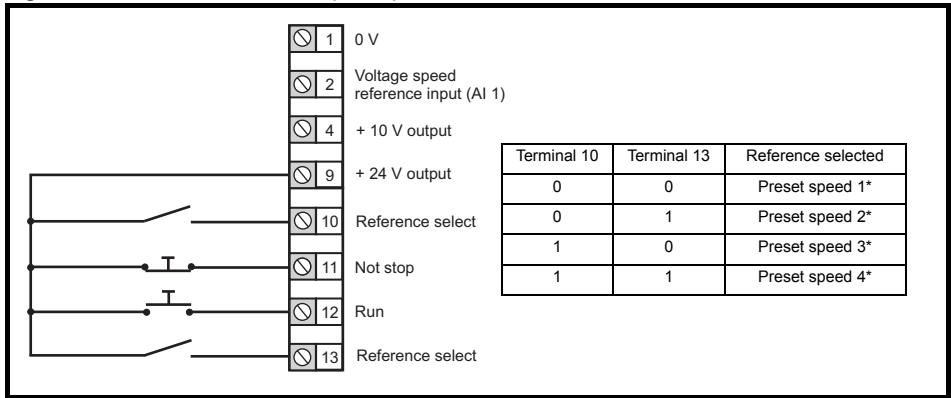


Figure 4-11 Pr 00.005 = Pad (50 Hz & 60 Hz)

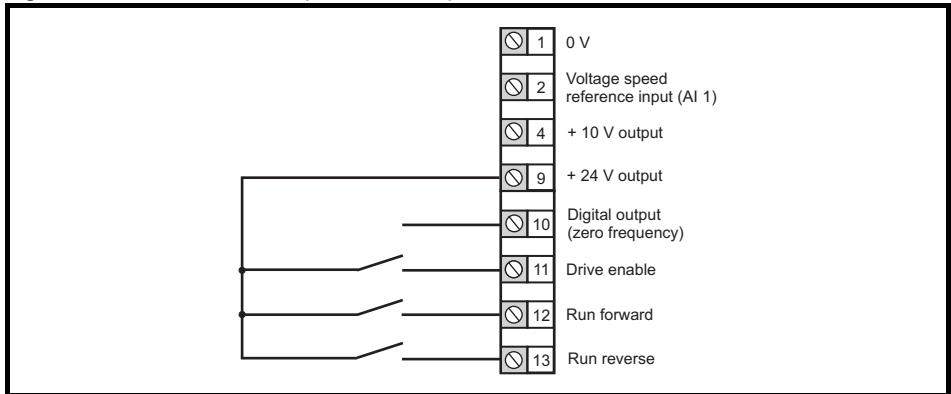
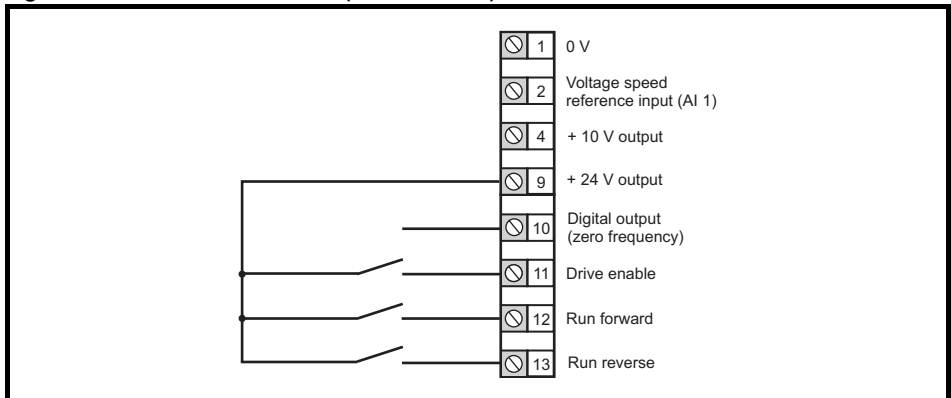


Figure 4-12 Pr 00.005 = Pad.Ref (50 Hz & 60 Hz)



* Refer to *Drive User Guide*.

Figure 4-13 Pr 00.005 = Torque (50 Hz)

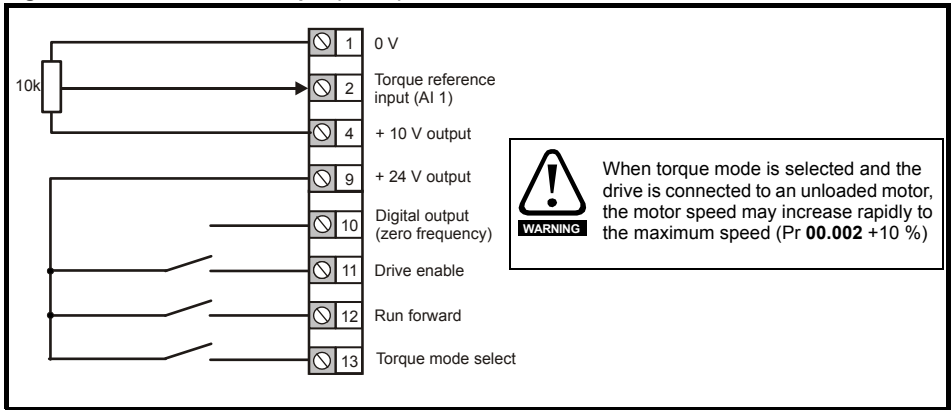
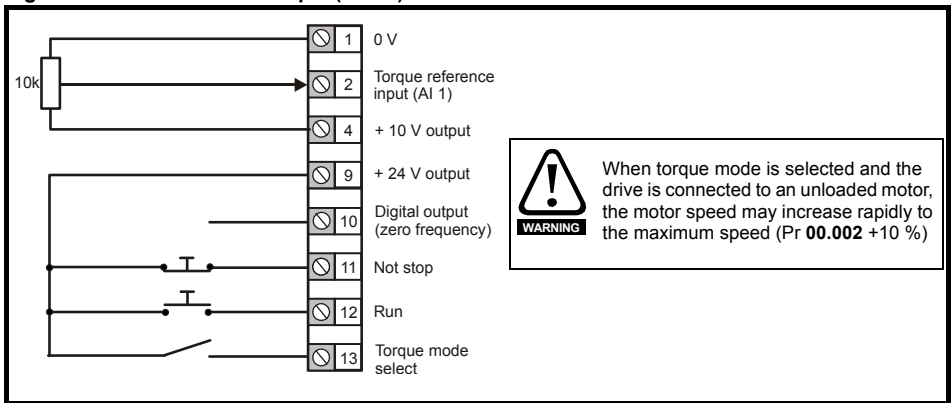


Figure 4-14 Pr 00.005 = Torque (60 Hz)



4.5 EMC

4.5.1 Internal EMC filter

It is recommended that the internal EMC filter be kept in place unless there is a specific reason for removing it. If the drive is used as a motoring drive as part of a regen system, then the internal EMC filter must be removed.

The internal EMC filter reduces radio-frequency emission into the line power supply.

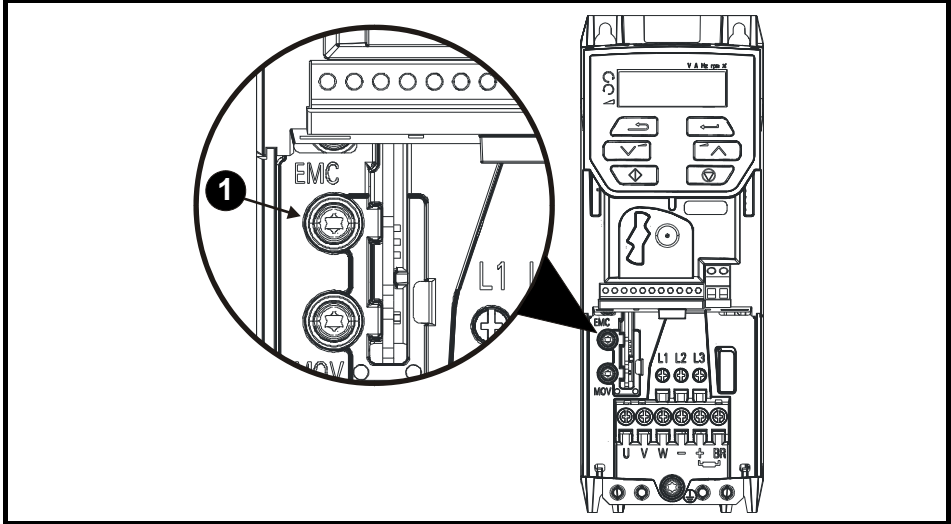
For longer motor cables, the filter continues to provide a useful reduction in emission levels and when used with any length of shielded motor cable up to the limit for the drive, it is unlikely that nearby industrial equipment will be disturbed. It is recommended that the filter be used in all applications unless the instructions given above require it to be removed, or where the ground leakage current is unacceptable.

4.5.2 Removing the internal EMC filter



The supply must be disconnected before removing the internal EMC filter.

Figure 4-15 Removal of the internal EMC filter (size 2 shown)



To electrically disconnect the internal EMC filter, remove the screw as shown above (1).

4.5.3 Further EMC precautions

Further EMC precautions are required if more stringent EMC emission requirements apply:

- Operation in the first environment of EN 61800-3: 2004
- Conformity to the generic emission standards
- Equipment which is sensitive to electrical interference operating nearby

In this case it is necessary to use:

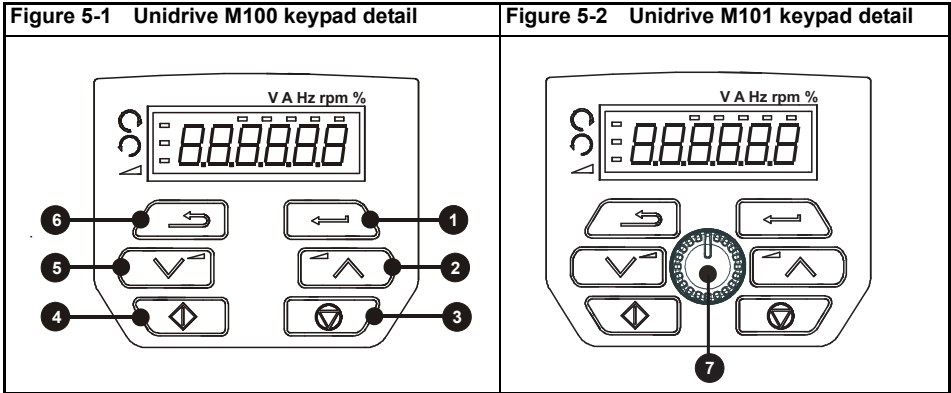
- The optional external EMC filter
- A shielded motor cable, with shield clamped to the grounded metal panel
- A shielded control cable, with shield clamped to the grounded metal panel

Full instructions are given in the *Drive User Guide*.

A full range of external EMC filters are also available for use with *Unidrive M100 / 101*, shown in the *Drive User Guide*.

5 Keypad and display

The keypad and display provide information to the user regarding the operating status of the drive and trip codes, and provide the means for changing parameters, stopping and starting the drive, and the ability to perform a drive reset.



- (1) The Enter button is used to enter parameter view or edit mode, or to accept a parameter edit.
- (2 / 5) The Navigation keys can be used to select individual parameters or to edit parameter values.
- (3) The Stop / Reset key is used to stop and reset the drive in keypad mode. It can also be used to reset the drive in terminal mode.
- (4) The Start key is used to start the drive in keypad mode.
- (6) The Escape key is used to exit from the parameter edit / view mode.
- (7) The Speed ref pot is used to control the speed reference in keypad mode (only on Unidrive M101).

Table 5-1 Status indications

String	Description	Drive output stage
inh	The drive is inhibited and cannot be run. The Drive Enable signal is not applied to the drive enable terminal or is set to 0. The other conditions that can prevent the drive from enabling are shown as bits in <i>Enable Conditions</i> . Refer to <i>Drive User Guide</i> .	Disabled
rdy	The drive is ready to run. The drive enable is active, but the drive inverter is not active because the final drive run is not active	Disabled
StoP	The drive is stopped / holding zero speed.	Enabled
S.Loss	Supply loss condition has been detected	Enabled
dc inj	The drive is applying dc injection braking	Enabled
Er	The drive has tripped and no longer controlling the motor. The trip code appears on the display.	Disabled
UV	The drive is in the under voltage state either in low voltage or high voltage mode.	Disabled

5.1 Saving parameters

When changing a parameter in Menu 0, the new value is saved when pressing the Enter button



to return to parameter view mode from parameter edit mode.

If parameters have been changed in the advanced menus, then the change will not be saved automatically. A save function must be carried out.

Procedure

1. Select 'Save**' in Pr **mm.000** (alternatively enter a value of 1001* in Pr **mm.000**)

• Press the red  reset button

* If the drive is in the under voltage state (i.e. when the AI-Backup adaptor terminals are being supplied from a +24 Vdc supply) a value of 1001 must be entered into Pr **mm.000** to perform a save function.

5.2 Restoring parameter defaults

Restoring parameter defaults by this method saves the default values in the drives memory. *User security status* (00.010) and *User security code* (00.025) are not affected by this procedure).

Procedure

1. Ensure the drive is not enabled, i.e. terminal 11 is open or OFF (0)

2. Select 'Def.50' or 'Def.60' in Pr **mm.000**. (alternatively, enter 1233 (50 Hz settings) or 1244 (60 Hz settings) in Pr **mm.000**).

Press the red  reset button

6 Basic parameters (Menu 0)

Menu 0 is used to bring together various commonly used parameters for basic easy set up of the drive. All the parameters in Menu 0 appear in other menus in the drive. Menu 22 can be used to configure the parameters in Menu 0.

6.1 Menu 0: Basic parameters

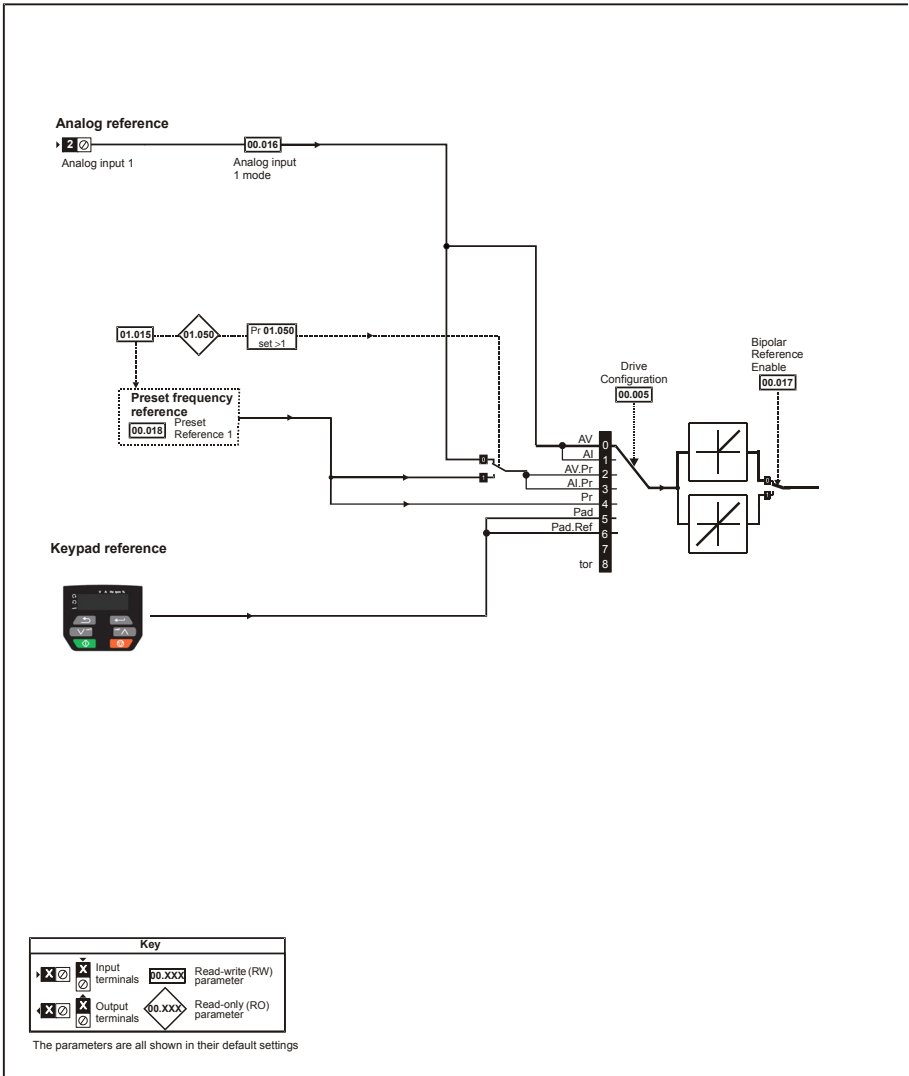
Parameter	Range (↕)	Default (⇔)	Type						
	OL	OL							
00.001	Minimum Reference Clamp	±VM_NEGATIVE_REF_CLAMP 1 Hz	0.00 Hz	RW	Num				US
00.002	Maximum Reference Clamp	±VM_POSITIVE_REF_CLAMP Hz	50 Hz default: 50.00 Hz 60 Hz default: 60.00 Hz	RW	Num				US
00.003	Acceleration Rate 1	±VM_ACCEL_RATE s	5.0 s	RW	Num				US
00.004	Deceleration Rate 1	±VM_ACCEL_RATE s	10.0 s	RW	Num				US
00.005	Drive Configuration	AV (0), AI (1), AV.Pr (2), AI.Pr (3), Preset (4), Pad (5), Pad.Ref (6), torque (8)	AV (0)*	RW	Txt			PT	US
00.006	Motor Rated Current	0.00 to VM_RATED_CURRENT A	Maximum Heavy Duty Rating (11.032) A	RW	Num		RA		US
00.007	Motor Rated Speed	0.0 to 80000.0 rpm	50 Hz default: 1500.0 rpm 60 Hz default: 1800.0 rpm	RW	Num				US
00.008	Motor Rated Voltage	0 to VM_AC_VOLTAGE_SET V	110 V drive: 230 V 200 V drive: 230 V 400 V drive 50 Hz: 400 V 400 V drive 60 Hz: 460 V	RW	Num		RA		US
00.009	Motor Rated Power Factor	0.00 to 1.00	0.85	RW	Num		RA		US
00.010	User Security Status	LEVEL.0 (0), ALL (1), r.only.0 (2), r.only.A (3), Status (4), no.acc(5)	LEVEL.0 (0)	RW	Num	ND	NC	PT	
00.015	Jog Reference	0.00 to 300.00 Hz	1.50 Hz	RW	Num				US
00.016	Analog Input 1 Mode	4-20.S (-6), 20-4.S (-5), 4-20.L (-4), 20-4.L (-3), 4-20.H (-2), 20-4.H (-1), 0-20 (0), 20-0 (1), 4-20.tr (2), 20-4.tr (3), 4-20 (4), 20-4 (5), Volt (6)	Volt (6)	RW	Txt				US
00.017	Bipolar Reference Enable	Off (0) or On (1)	Off (0)	RW	Bit				US
00.018	Preset Reference 1	±VM_SPEED_FREQ_REF Hz	0.00 Hz	RW	Num				US
00.025	User Security Code	0 to 9999	0	RW	Num	ND	NC	PT	US
00.027	Power-up Keypad Control Mode Reference	Reset (0), Last (1), Preset (2)	Reset (0)	RW	Txt				US
00.028	Ramp Mode Select	Fast (0), Std (1), Std.bst (2), Fst.bst (3)	Std (1)	RW	Txt				US
00.030	Parameter Cloning	None (0), rEAd (1), Prog (2), Auto (3), boot (4)	None (0)	RW	Txt		NC		US
00.031	Stop Mode	Coast (0), rp (1), rp.dc I (2), dc I (3), td.dc I (4),dis (5), No.rp (6)	rp (1)	RW	Txt				US
00.032	Dynamic V to F Select	0 to 1	0	RW	Num				US
00.033	Catch A Spinning Motor	dis (0), Enable (1), Fr.Only (2), Rv.Only (3)	dis (0)	RW	Txt				US
00.035	Digital Output 1 Control	0 to 21	0	RW					US
00.037	Maximum Switching Frequency	0.667 (0), 1 (1), 2 (2), 3 (3), 4 (4), 6 (5), 8 (6), 12 (7), 16 (8) kHz	3 (3) kHz	RW	Txt				US

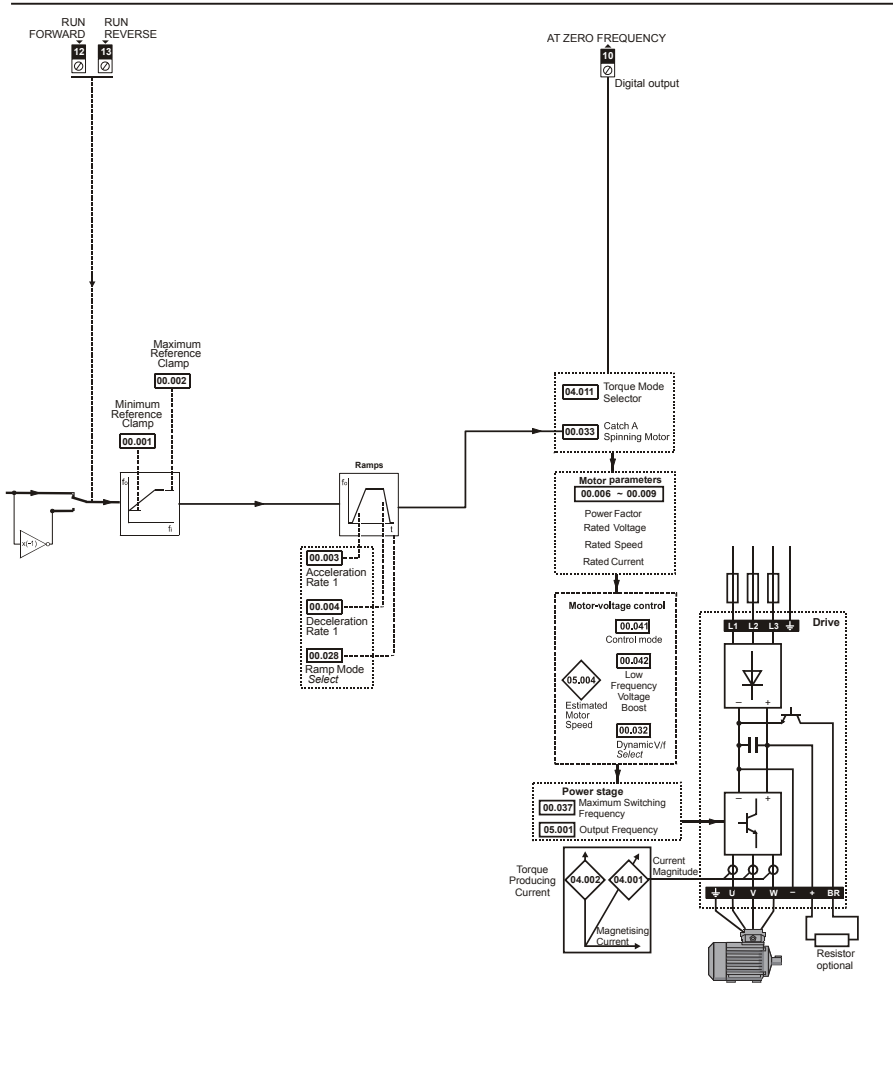
Parameter		Range (⌘)	Default (⇒)	Type					
		OL	OL						
00.038	Autotune	0 to 2	0	RW	Num		NC		US
00.039	Motor Rated Frequency	0.00 to VM_SPEED_FREQ_REF_UNIPOLAR Hz	50 Hz: 50.00 Hz 60 Hz: 60.00 Hz	RW	Num				US
00.040	Number of Motor Poles	Auto (0) to 32 (16)	Auto 0	RW	Num				US
00.041	Control Mode	Ur.S (0), Ur (1), Fd (2), Ur.Auto (3), Ur.I (4), SrE (5), Fd.tap (6)	Ur.I (4)	RW	Txt				US
00.042	Low Frequency Voltage Boost	0.0 to 25.0 %	3.0 %	RW	Num				US
00.069	Spin Start Boost	0.0 to 10.0	1.0	RW					US
00.076	Action on Trip Detection	0 to 31	0	RW					US
00.077	Maximum Heavy Duty Current Rating	0.00 to 9999.99 A		RO	Num	ND	NC	PT	
00.078	Software Version	0 to 999999		RO		ND	NC	PT	
00.079	User Drive Mode	OPEn.LP (1)	OPEn.LP (1)	RW	Txt	ND	NC	PT	US

* With Unidrive M101, the default is Pad (5).

RW	Read / Write	RO	Read only	Num	Number parameter	Bit	Bit parameter	Txt	Text string	Bin	Binary parameter	FI	Filtered
ND	No default value	NC	Not copied	PT	Protected parameter	RA	Rating dependent	US	User save	PS	Power-down save	DE	Destination

Figure 6-1 Menu 0 logic diagram





6.2 Unidrive M100/101 parameter descriptions

Key:

RW	Read / Write	RO	Read only	Num	Number parameter	Bit	Bit parameter	Txt	Text string	Bin	Binary parameter	FI	Filtered
ND	No default value	NC	Not copied	PT	Protected parameter	RA	Rating dependent	US	User save	PS	Power-down save	DE	Destination

00.001 {01.007}		Minimum Reference Clamp												
RW		Num										US		
OL	⇕	±VM_NEGATIVE_REF_CLAMP1 Hz						⇒	0.00 Hz					

Set Pr **00.001** at the required minimum output frequency of the drive for both directions of rotation. The drive speed reference is scaled between Pr **00.001** and Pr **00.002**. Pr **00.001** is a nominal value; slip compensation may cause the actual frequency to be higher. When the drive is jogging, Pr **00.001** has no effect.

00.002 {01.006}		Maximum Reference Clamp												
RW		Num										US		
OL	⇕	±VM_POSITIVE_REF_CLAMP Hz						⇒	50.00 Hz default: 50.00 Hz 60.00 Hz default: 60.00 Hz					

Set Pr **00.002** at the required maximum output frequency for both directions of rotation. The drive speed reference is scaled between Pr **00.001** and Pr **00.002**. Pr **00.002** is a nominal value; slip compensation may cause the actual frequency to be higher. The drive has additional over-speed protection.

00.003 {02.011}		Acceleration Rate 1												
RW		Num										US		
OL	⇕	±VM_ACCEL_RATE s/100 Hz						⇒	5.0 s/100 Hz					

Set Pr **00.003** at the required rate of acceleration. Note that larger values produce lower acceleration. The rate applies in both directions of rotation.

00.004 {02.021}		Deceleration Rate 1												
RW		Num										US		
OL	⇕	±VM_ACCEL_RATE s/100 Hz						⇒	10.0 s/100 Hz					

Set Pr **00.004** at the required rate of deceleration. Note that larger values produce lower deceleration. The rate applies in both directions of rotation.

00.005 {11.034}		Drive Configuration								
RW	Txt						PT	US		
OL	⇕	AV (0), AI (1), AV.Pr (2), AI.Pr (3), Preset (4), Pad (5), Pad.Ref (6), torque (8)				⇒	AV (0)			

Use Pr **00.005** to select the required frequency/speed reference as follows:

Value	Text	Description
0	AV	Analog input 1 (voltage)
1	AI	Analog input 1 (current)
2	AV.Pr	Analog input 1 (voltage) or 3 presets selected by terminal
3	AI.Pr	Analog input 1 (current) or 3 presets selected by terminal
4	Preset	Four presets selected by terminal
5	Pad	Keypad reference
6	Pad.Ref	Keypad reference with terminal control
8	torque	Torque mode, Analog input 1 (voltage torque reference) selected by terminal

NOTE A change to Pr **00.005** is set by pressing the MODE key on exit from parameter edit mode. The drive must be disabled, stopped or tripped for a change to take place. If Pr **00.005** is changed while the drive is running, when the MODE key is pressed on exit from parameter edit mode, Pr **00.005** will change back to its previous value.

NOTE When the setting of Pr **00.005** is changed, the appropriate drive configuration parameters are set back to their default values.

00.006 {05.007}		Motor Rated Current								
RW	Num					RA		US		
OL	⇕	0.00 to VM_RATED_CURRENT A				⇒	Maximum Heavy Duty Rating A*			

* Refer to the *Drive User Guide*.

The rated current parameter must be set to the maximum continuous current of the motor (taken from the name plate). The motor rated current is used in the following:

- Current limits
- Motor thermal overload protection
- Vector mode voltage control
- Slip compensation (see *Enable Slip Compensation*). Refer to the *Drive User Guide*.
- Dynamic V/F control

00.007 {05.008}		Motor Rated Speed								
RW	Num							US		
OL	⇕	0.0 to 80000.0 rpm				⇒	50Hz default: 1500.0 rpm 60Hz default: 1800.0 rpm			

Set to the rated speed of the motor (taken from the motor name plate). The motor rated speed is used to calculate the correct slip speed for the motor.

00.008 {05.009}		Motor Rated Voltage								
RW	Num					RA		US		
OL	⇕	0 to VM_AC_VOLTAGE_SET				⇒	110 V drive: 230 V 200 V drive: 230 V 400 V drive 50 Hz: 400 V 400 V drive 60 Hz: 460 V			

The *Rated Voltage* (00.008) and the *Rated Frequency* (00.039) are used to define the voltage to frequency characteristic applied to the motor. The *Rated Frequency* (00.039) is also used in conjunction with the *Motor Rated Speed* (00.007) to calculate the rated slip for slip compensation.

00.009 {05.010}		Motor Rated Power Factor								
RW	Num					RA		US		
OL	⇕	0.00 to 1.00				⇒	0.85			

Enter the motor rated power factor $\cos \phi$ (taken from the motor name plate).

The drive can measure the motor rated power factor by performing a rotating autotune (see Autotune (Pr 00.038)).

00.010 {11.044}		User Security Status								
RW	Num					ND	NC	PT	US	
OL	⇕	LEVEL.0 (0), ALL (1), r.only.0 (2), r.only.A (3), Status (4), no.Acc (5)				⇒	LEVEL.0 (0)			

This parameter controls access via the drive keypad as follows:

Value	Text	Function
0	Menu 0 (LEVEL.0)	All writable parameters are available to be edited but only parameters in Menu 0 are visible.
1	All Menus (ALL)	All writable parameters are visible and available to be edited.
2	Read-only Menu 0 (r.only.0)	All parameters are read-only. Access is limited to Menu 0 parameters only.
3	Read-only (r.only.A)	All parameters are read-only however all menus and parameters are visible.
4	Status Only (Status)	The keypad remains in status mode and no parameters can be viewed or edited.
5	No Access (no.Acc)	The keypad remains in status mode and no parameters can be viewed or edited. Drive parameters cannot be accessed via a comms/fieldbus interface in the drive or any option module.

00.015 {01.005}		Jog Reference							
RW	Num							US	
OL	⇕	0.00 to 300.00 Hz			⇒	1.50 Hz			

Defines the reference when jog is enabled.

00.016 {07.007}		Analog Input 1 Mode							
RW	Txt							US	
OL	⇕	4-20.S (-6), 20-4.S (-5), 4-20.L (-4), 20-4.L (-3), 4-20.H (-2), 20-4.H (-1), 0-20 (0), 20-0 (1), 4-20.tr (2), 20-4.tr (3), 4-20 (4), 20-4 (5), Volt (6)			⇒	Volt (6)			

Defines the mode of analog input 1.

The table below gives all the possible analog input modes.

Value	Text	Function
-6	4-20.S	Stop on loss
-5	20-4.S	Stop on loss
-4	4-20.L	4-20 mA switching to equivalent of 4 mA input current on loss
-3	20-4.L	20-4 mA switching to equivalent of 20 mA input current on loss
-2	4-20.H	4-20 mA hold at level before loss on loss
-1	20-4.H	20-4 mA hold at level before loss on loss
0	0-20	0-20 mA
1	20-0	20-0 mA
2	4-20.tr	4-20 mA trip on loss
3	20-4.tr	20-4 mA trip on loss
4	4-20	4-20 mA no action on loss
5	20-4	20-4 mA no action on loss
6	Volt	Voltage

NOTE In 4-20 mA and 20-4 mA modes loss of input is detected if the current falls below 3 mA.

NOTE If both analog inputs (A1 and A2) are to be set-up as voltage inputs, and if the potentiometers are supplied from the drive's +10 V rail (terminal T3), they must have a resistance >4 kΩ each.

00.017 {01.010}		Bipolar Reference Enable								
RW	Bit							US		
OL	⇕	Off (0) or On (1)				⇒	Off (0)			

Pr **00.017** determines whether the reference is uni-polar or bi-polar.

See *Minimum Reference Clamp* (00.001). Allows negative speed reference in keypad mode.

00.018 {01.021}		Preset Reference 1								
RW	Num							US		
OL	⇕	±VM_SPEED_FREQ_REF				⇒	0.00 Hz			

If the preset reference has been selected (see Pr **00.005**), the speed at which the motor runs is determined by this parameter.

See *Drive Configuration* (00.005).

00.025 {11.030}		User Security Code								
RW	Num				ND	NC	PT	US		
OL	⇕	0-9999				⇒	0			

If any number other than 0 is programmed into this parameter, user security can be applied so that no parameters except Pr **00.010** can be adjusted with the keypad. When this parameter is read via a keypad it appears as zero. Refer to the *Drive User Guide* for further information.

00.027 {01.051}		Power-up Keypad Control Mode Reference								
RW	Txt				ND	NC	PT	US		
OL	⇕	Reset (0), Last (1), Preset (2)				⇒	Reset (0)			

Defines which value of keypad control mode reference is displayed at power-up.

Value	Text	Description
0	Reset	Keypad reference is zero
1	Last	Keypad reference is the last used value
2	Preset	Keypad reference is copied from <i>Preset Reference 1</i> (00.018)

00.028 {02.004}		Ramp Mode Select							
RW	Txt							US	
OL	⇅	Fast (0), Std (1), Std.bst (2), Fst.bst (3)				⇒	Std (1)		

Defines the mode used by the ramp system.

- 0:** Fast ramp
- 1:** Standard ramp
- 2:** Standard ramp with motor voltage boost
- 3:** Fast ramp with motor voltage boost

Fast ramp is linear deceleration at programmed rate, normally used when a braking resistor is installed.

Standard ramp is controlled deceleration to prevent DC bus over-voltage trips, normally used when there is no braking resistor installed.

If a high motor voltage mode is selected, deceleration rates can be faster for a given inertia but motor temperatures will be higher.

00.030 {11.042}		Parameter Cloning							
RW	Txt					NC		US*	
OL	⇅	None (0), Read (1), Program (2), Auto (3), Boot (4)				⇒	None (0)		

* Only a value of 3 or 4 in this parameter is saved.

If Pr **00.030** is equal to 1 or 2, this value is not transferred to the EEPROM or the drive. If Pr **00.030** is set to a 3 or 4 the value is transferred.

Parameter string	Parameter value	Comment
None	0	Inactive
Read	1	Read parameter set from the NV Media Card
Program	2	Programming a parameter set to the NV Media Card
Auto	3	Auto save
Boot	4	Boot mode

For further information, please refer to Chapter 9 *NV Media Card Operation* on page 42.

00.031 {06.001}		Stop Mode							
RW	Txt							US	
OL	⇕	Coast (0), rp (1), rp.dc l (2), dc l (3), td.dc l (4), dis (5), No.rp (6)				⇒	rp (1)		

Defines how the motor is controlled when the run signal is removed from the drive.

Value	Text	Description
0	Coast	Coast stop
1	rp	Ramp stop
2	rP.dcl	Ramp stop + 1 second dc injection
3	dc l	Injection braking stop with detection of zero speed
4	td.dcl	Timed injection braking stop
5	Dis	Disable
6	No.rP	No ramp

See the *Drive User Guide* for further information.

00.032 {05.013}		Dynamic V To F Select							
RW	Num							US	
OL	⇕	0 to 1				⇒	0		

Set to 1 to enable Dynamic V to F mode.

0:Fixed linear voltage to frequency ratio (constant torque - standard load)

1: Voltage to frequency ratio dependant on load current. This gives a higher motor efficiency.

00.033 {06.009}		Catch a Spinning Motor							
RW	Num							US	
OL	⇕	dis (0), Enable (1), Fr.Only (2), Rv.Only (3)				⇒	dis (0)		

If the drive is to be configured in fixed boost mode (Pr **00.041** = Fd or SrE) with catch a spinning motor software enabled, an autotune (see Pr **00.038** on page 34) must be carried out to measure the motor's stator resistance beforehand. If a stator resistance is not measured, the drive may trip on 0 V or OI.AC while trying to catch a spinning motor.

Pr 00.033	Text	Function
0	Dis	Disabled
1	Enable	Detect all frequencies
2	Fr.Only	Detect positive frequencies only
3	Rv.Only	Detect negative frequencies only

00.035 {08.091}		DO1 Control (terminal 10)							
RW	Num							US	
OL	⇅	0-21			⇒	0			

Defines the behaviour of digital output 1.

Value	Description
0	User defined by Digital IO1 Source/Destination A, Digital IO2 Source/Destination A, <i>Relay 1 Output Source A</i> , or Relay 2 Output Source A.
1	Drive running signal (RUN)
2	Frequency arrived signal (FAR)
3	Frequency level detection signal (FDT1)
4	Frequency level detection signal (FDT2)
5	Overload detection signal (OL)
6	Power off state (LU)
7	External fault stop (EXT)
8	Frequency upper limit (FHL)
9	Frequency lower limit (FLL)
10	Drive running at zero frequency
14	Drive (RDY)
15	Drive OK
18	Brake release
19	Torque limiting (Valid while the torque is limited by torque limiting value 1/2)
20	Forward or reverse
21	Motor 1 or 2

For further information, refer to the *Drive User Guide*.

00.037 {05.018}		Maximum Switching Frequency								
RW	Txt							US		
OL	↕	0.667 (0), 1 (1), 2 (2), 3 (3), 4 (4), 6 (5), 8 (6), 12 (7), 16 (8) kHz				⇒	3 (3) kHz			

Defines the maximum switching frequency that can be used by the drive.

Pr 00.037	Text	Description
0	0.667	667 Hz switching frequency
1	1	1 kHz switching frequency
2	2	2 kHz switching frequency
3	3	3 kHz switching frequency
4	4	4 kHz switching frequency
5	6	6 kHz switching frequency
6	8	8 kHz switching frequency
7	12	12 kHz switching frequency
8	16	16 kHz switching frequency

See the *Drive User Guide* for drive derating data.

00.038 {05.012}		Autotune								
RW	Num					NC		US		
OL	↕	0-2				⇒	0			

Defines the auto-tune test to be performed.

There are two autotune tests available in open loop mode, a stationary and a rotating test. A rotating autotune should be used whenever possible so the measured value of power factor of the motor is used by the drive.

1. A stationary autotune can be used when the motor is loaded and it is not possible to remove the load from the motor shaft. To perform a Stationary autotune, set Pr **00.038** to 1,
2. A rotating autotune should only be used if the motor is unloaded. A rotating autotune first performs a stationary autotune, as above, then a rotating test is performed in which the motor is accelerated with currently selected ramps up to a frequency of *Rated Frequency* (00.039) x 2/3, and the frequency is maintained at that level for 4 seconds. To perform a Rotating autotune, set Pr **00.038** to 2.

Following the completion of an autotune test the drive will go into the inhibit state. The drive must be placed into a controlled disable condition before the drive can be made to run at the required reference. The drive can be put in to a controlled disable condition by removing the signal from terminal 11, setting the *Drive Enable* to OFF (0). For further information, refer to the *Drive User Guide*



A rotating autotune will cause the motor to accelerate up to 2/3 base speed in the direction selected regardless of the reference provided. Once complete the motor will coast to a stop. The enable signal must be removed before the drive can be made to run at the required reference. The drive can be stopped at any time by removing the run signal or removing the drive enable.

00.039 {05.006}		Motor Rated Frequency							
RW	Num							US	
OL	⇅	0.00 to VM_SPEED_FREQ_REF_ UNIPOLAR Hz			⇒	50 Hz: 50.00 Hz 60 Hz: 60.00 Hz			

Enter the value from the rating plate of the motor. Defines the voltage to frequency ratio applied to the motor.

00.040 {05.011}		Number Of Motor Poles							
RW	Num							US	
OL	⇅	Auto (0) to 32 (16)			⇒	Auto (0)			

Set to the number of poles of the motor. The auto mode calculates the number of motor poles from the settings of Pr 00.007 and Pr 00.039.

00.041 {05.014}		Control Mode							
RW	Txt							US	
OL	⇅	Ur.S (0), Ur (1), Fd (2), Ur.Auto (3), Ur.I (4), SrE (5), Fd.tap (6)			⇒	Ur.I (4)			

Defines the drive output mode, which can either be a voltage mode or a current mode.

Value	Text	Description
0	Ur.S	Stator resistance and voltage offset measured at each start
1	Ur	No measurements
2	Fd	Fixed boost mode.
3	Ur.Auto	Stator resistance and voltage offset measured at first drive enable
4	Ur.I	Stator resistance and voltage offset measured at each power-up
5	SrE	Square law characteristic
6	Fd.tap	Fixed boost with taper

NOTE The drive default setting is Ur I mode which means that the drive will carry out an autotune every time the drive is powered-up and enabled. If the load is not going to be stationary when the drive is powered-up and enabled, then one of the other modes should be selected. Not selecting another mode could result in poor motor performance or OI.AC, It.AC or 0 V trips.

00.042 {05.015}		Low Frequency Voltage Boost							
RW	Num							US	
OL	⇅	0.0 to 25.0 %			⇒	3 %			

Determines the boost level when Pr 00.041 is set to Fd, SrE or Fd.tap modes.

00.069 {05.040}		Spin Start Boost							
RW	Num							US	
OL	⇕	0.0 to 10.0			⇒	1.0			

Spin Start Boost (00.069) is used by the algorithm that detects the frequency of a spinning motor when the drive is enabled and *Catch A Spinning Motor* (00.033) ≥ 1 . For smaller motors the default value of 1.0 is suitable, but for larger motors *Spin Start Boost* (00.069) may need to be increased.

00.076 {10.037}		Action On Trip Detection							
RW	Num				ND	NC	PT	US	
OL	⇕	0 - 31			⇒	0			

Defines the action of the drive on detection of a trip.

Bit 0: Stop on defined non-important trips

Bit 1: Disable braking resistor overload detection

Bit 2: Disable phase loss stop

Bit 3: Disable braking resistor temperature monitoring

Bit 4: Disable parameter freeze on trip. Refer to *Drive User Guide*.

00.077 {11.032}		Maximum Heavy Duty Rating							
RO	Num				ND	NC	PT		
OL	⇕	0.00 to 9999.99 A			⇒				

Displays the maximum heavy duty current rating of the drive.

00.078 {11.029}		Software Version							
RO	Num				ND	NC	PT		
OL	⇕	0 to 999999			⇒				

Displays the software version in the drive.

00.079 {11.031}		User Drive Mode							
RW	Txt				ND	NC	PT	US	
OL	⇕	OPEn.LP (1)			⇒	OPEn.LP (1)			

The user drive mode is open-loop only.

7 Running the motor

This section takes a new user through all the essential steps to running a motor for the first time.

Table 7-1 Open Loop

Action	Detail	
Before power up	<p>Ensure:</p> <ul style="list-style-type: none"> The drive enable signal is not given, terminal 11 is open The run signal is not given, terminal 12/13 is open The motor is connected to the drive The motor connection is correct for the drive Δ or Y The correct supply voltage is connected to the drive 	
Power up the drive	<p>Ensure:</p> <ul style="list-style-type: none"> The drive displays: InH 	
Enter minimum and maximum speeds	<p>Enter:</p> <ul style="list-style-type: none"> Minimum speed Pr 00.001 (Hz) Maximum speed Pr 00.002 (Hz) 	
Enter accel and decel rates	<p>Enter:</p> <ul style="list-style-type: none"> Acceleration rate Pr 00.003 (s/100 Hz) Deceleration rate Pr 00.004 (s/100 Hz) 	
Enter motor nameplate details	<p>Enter:</p> <ul style="list-style-type: none"> Motor rated current in Pr 00.006 (A) Motor rated speed in Pr 00.007 (rpm) Motor rated voltage in Pr 00.008 (V) Motor rated power factor in Pr 00.009 If the motor is not a standard 50/60 Hz motor, set Pr 00.039 accordingly 	
Ready to autotune		
Autotune	<p>The drive is able to perform either a stationary or a rotating autotune. The motor must be at a standstill before an autotune is enabled. To perform an autotune:</p> <ul style="list-style-type: none"> Set Pr 00.038 = 1 for a stationary autotune or set Pr 00.038 = 2 for a rotating autotune Close the drive enable signal (Apply +24 V to terminal 11). The drive will display 'Rdy'. Close the run signal (Apply +24 V to terminal 12 or 13). The display will flash 'tuning' while the drive is performing the autotune. Wait for the drive to display 'InH' and for the motor to come to a standstill. <p>Remove the drive enable and run signal from the drive.</p>	
Autotune complete	When the autotune has been completed, Pr 00.038 will be set to 0	
Save parameters		
Save parameters	Select 'SAVE' in Pr mm.000 (alternatively enter a value of 1001) and press the Stop / Reset button to save parameters.	
Ready to run		
Run	The drive is now ready to run the motor.	
Increasing and decreasing speed	Turning the speed potentiometer will increase and decrease the speed of the motor.	
Stopping	To stop the motor under ramp control, open either the run forward or run reverse terminal. If the enable terminal is opened while the motor is running, the motor will coast to a stop.	

8 Diagnostics



Users must not attempt to repair a drive if it is faulty, nor carry out fault diagnosis other than through the use of the diagnostic features described in this chapter. If a drive is faulty, it must be returned to the supplier of the drive for repair.

Table 8-1 Trip indications

Trip code	Condition	Description
C.Acc	NV Media Card Write fail	Unable to access the NV Media Card.
C.bt	The Menu 0 parameter modification cannot be saved to the NV Media Card	The necessary boot file has not been created on the NV media card fitted to the drive to take the new parameter value. This occurs when <i>Parameter Cloning</i> (00.030) is changed to auto or boot mode, but the drive is not subsequently reset.
C.cPr	NV Media Card file/data is different to the one in the drive	A <i>C.cPr</i> trip is initiated if the parameters on the NV Media Card are different to the drive.
C.d.E	NV Media Card data location already contains data	Attempt has been made to store data on a NV Media Card in a data block which already contains data.
C.dAt	NV Media Card data not found	Attempt has been made to access non existent file or block on the NV Media Card.
C.Err	NV Media Card data structure error	Attempt has been made to access the NV Media Card but an error has been detected in the data structure on the card. Resetting the trip will cause the drive to erase and create the correct folder structure.
C.FuL	NV Media Card full	There is not enough space left on the card.
C.Pr	NV Media Card data blocks are not compatible with the drive derivative	If <i>Drive Derivative</i> is different between the source and target drives. Refer to <i>Drive User Guide</i> .
C.rdo	NV Media Card has the Read Only bit set	Attempt has been made to modify a read-only NV Media Card or a read-only data block.
C.rtg	NV Media Card Trip; The voltage and / or current rating of the source and destination drives are different	The current and / or voltage ratings are different between source and destination drives.
C.tyP	NV Media Card parameter set not compatible with current drive mode	The drive mode in the data block on the NV Media Card is different from the current drive mode.
cL.A1	Analog input 1 current loss	Current loss was detected in current mode on Analog input 1 (Terminal 2).
Cur.c	Current calibration range	Current calibration range error.
Cur.O	Current feedback offset error	Current offset is too large to be trimmed.
d.Ch	Drive parameters are being changed	A user action or a file system write is active that is changing the drive parameters and the drive has been commanded to enable.
dEr.E	Derivative file error	Contact the supplier of the drive.
dEr.I	Derivative product image error	Contact the supplier of the drive.
dEst	Two or more parameters are writing to the same destination parameter	The dEst trip indicates that destination output parameters of two or more logic functions (Menus 7 and 8) within the drive are writing to the same parameter.
dr.CF	Drive configuration	Contact the supplier of the drive.
EEF	Default parameters have been loaded	The EEF trip indicates that default parameters have been loaded. The exact cause/reason of the trip can be identified from the sub-trip number (see <i>Drive User Guide</i>).

Trip code	Condition	Description				
Et	An External trip is initiated	The cause of the trip can be identified from the sub trip number displayed after the trip string.				
		<table border="1"> <thead> <tr> <th>Sub-trip</th> <th>Reason</th> </tr> </thead> <tbody> <tr> <td>1</td> <td>External Trip = 1</td> </tr> </tbody> </table>	Sub-trip	Reason	1	External Trip = 1
		Sub-trip	Reason			
1	External Trip = 1					
Refer to <i>Drive User Guide</i> .						
FAN.F	Fan fail	Indicates the fan or fan circuitry has failed				
Fi.Ch	File changed	A file has been changed, power cycle to clear the trip				
Fl.In	Firmware Incompatibility	The user firmware is incompatible with the power firmware.				
HFxx trip	Hardware faults	Internal drive hardware fault (see <i>Drive User Guide</i>)				
It.Ac	Output current overload timed out (I^2t)	<p>The It.Ac trip indicates a motor thermal overload based on the output current and motor thermal time constant. The drive will trip on It.Ac when the accumulator gets to 100 %.</p> <p>This can occur when:</p> <ul style="list-style-type: none"> • There is excessive mechanical load • Ensure the load is not jammed / sticking • Check the load on the motor has not changed • Ensure the motor rated current is not zero 				
It.br	Braking resistor overload timed out (I^2t)	Braking resistor overload has timed out. This can be caused by excessive braking resistor energy.				
no.PS	No power board	No communication between the power and control boards.				
O.Ld1	Digital output overload	The total current drawn from 24 V user supply or from the digital output has exceeded the limit.				
O.SPd	Motor frequency has exceeded the over frequency threshold	Excessive motor speed (typically caused by mechanical load driving the motor).				
Oh.br	Braking IGBT over-temperature	Braking IGBT over-temperature. Detected by thermal model				
Oh.dc	DC bus over temperature	DC bus component over temperature based on a software thermal model.				
Oht.C	Control stage over-temperature	Control stage over-temperature detected.				
Oht.I	Inverter over temperature based on thermal model	IGBT junction over-temperature has been detected based on a software thermal model.				
Oht.P	Power stage over temperature	This trip indicates that a power stage over-temperature has been detected.				
Oht.r	Rectifier over temperature	The Oht.r trip indicates that a rectifier over-temperature has been detected.				
OI.A1	Analog input 1 over-current	Current input on analog input 1 exceeds 24 mA.				
OI.AC	Instantaneous output over current detected	<p>The instantaneous drive output current has exceeded. The set limit.</p> <p>Possible solutions:</p> <ul style="list-style-type: none"> • Increase acceleration/deceleration rate • If seen during autotune reduce the voltage boost • Check for short circuit on the output cabling • Check integrity of the motor insulation using an insulation tester • Is the motor cable length within limits for the frame size • Reduce the values in the current loop gain parameters 				
OI.br	Braking IGBT over current detected: short circuit protection for the braking IGBT activated	<p>Over current has been detected in braking IGBT or braking IGBT protection has been activated.</p> <p>Possible cause:</p> <ul style="list-style-type: none"> • Check brake resistor wiring • Check braking resistor value is greater than or equal to the minimum resistance value • Check braking resistor insulation 				

Trip code	Condition	Description
OI.SC	Output phase short-circuit	Over-current detected on drive output when enabled.
Out.P	Output phase loss detected	Phase loss has been detected at the drive output.
OV	DC bus voltage has exceeded the peak level or maximum continuous level for 15 seconds	The OV trip indicates that the DC bus voltage has exceeded the maximum limit. Possible solutions: <ul style="list-style-type: none"> • Increase <i>Deceleration Rate 1</i> (Pr 00.004) • Decrease the braking resistor value (staying above the minimum value) • Check nominal AC supply level • Check for supply disturbances which could cause the DC bus to rise • Check motor insulation using a insulation tester
P.dAt	Power system configuration data error	Contact the supplier of the drive.
Pb.Er	Communication has been lost / errors detected between power control	Communications loss between power and control.
Pb.HF	Power board HF	Power processor hardware fault - contact the supplier of the drive
Pd.S	Power down save error	Error has been detected in the power down save parameters saved in non-volatile memory.
PH.Lo	Supply phase loss	The drive has detected an input phase loss or large supply imbalance.
PSU	Internal power supply fault	One or more internal power supply rails are outside limits or overloaded.
r.b.ht	Hot rectifier/brake	Over-temperature detected on input rectifier or braking IGBT.
rS	Measured resistance has exceeded the parameter range	The measured stator resistance during an autotune test has exceeded the maximum possible value of <i>Stator Resistance</i> . Refer to the <i>Drive User Guide</i> .
So.St	Soft start relay failed to close, soft start monitor failed	Soft start relay in the drive failed to close or the soft start monitoring circuit has failed.
St.HF	Hardware trip has occurred during last power down	Hardware trip (HF01 –HF19) has occurred and the drive has been power cycled. Enter 1299 to xx.000 to clear trip
th.br	Brake resistor over temperature	The th.br trip is initiated if the hardware based braking resistor thermal monitoring is connected and the resistor overheats.
tH.Fb	Internal thermistor has failed	Internal thermistor has failed.
tun.S	Autotune test stopped before completion	The drive was prevented from completing an autotune test, because either the drive enable or the drive run signals were removed.
U.OI	User OI ac	The U.OI trip is initiated if the output current of the drive exceeds the trip level set by <i>User Over Current Trip Level</i> . Refer to the <i>Drive User Guide</i> .
U.S	User Save error / not completed	The U.S trip indicates that an error has been detected in the user save parameters saved in non-volatile memory.
US.24	User 24 V supply is not present on the adaptor interface terminals (1,2)	A US.24 trip is initiated if the <i>User Supply Select</i> is set to 1 and no user 24 V supply is present on the user 24 V input on the AI-Backup adaptor.Refer to the <i>Drive User Guide</i>

8.1 Alarm indications

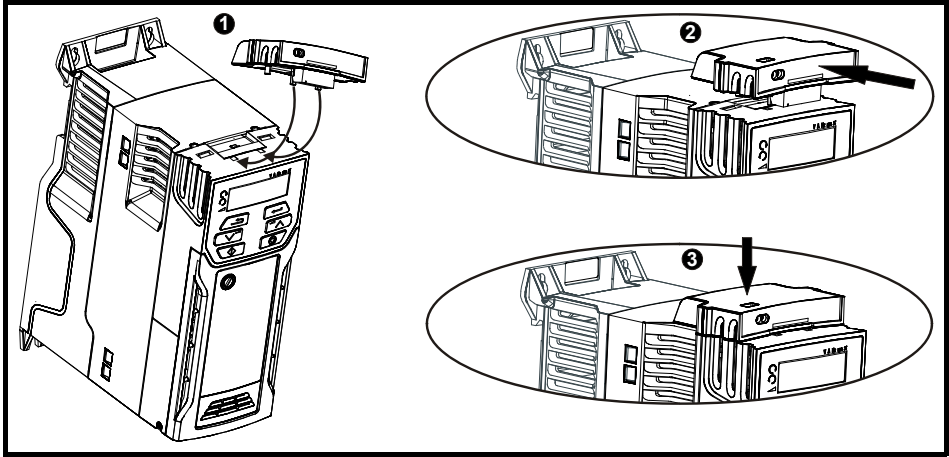
In any mode, an alarm is an indication given on the display by alternating the alarm string with the drive status string display. If an action is not taken to eliminate any alarm except "tuning and LS" the drive may eventually trip. Alarms are not displayed when a parameter is being edited.

Table 8-2 Alarm indications

Alarm string	Description
br.res	Brake resistor overload. <i>Braking Resistor Thermal Accumulator</i> in the drive has reached 75.0 % of the value at which the drive will trip.Refer to the <i>Drive User Guide</i>
OV.Ld	<i>Motor Protection Accumulator</i> in the drive has reached 75.0 % of the value at which the drive will trip and the load on the drive is >100 %, reduce motor current (load). Refer to the <i>Drive User Guide</i>
d.OV.Ld	Drive over temperature. <i>Percentage Of Drive Thermal Trip Level</i> in the drive is greater than 90 %. Refer to the <i>Drive User Guide</i>
tuning	The autotune procedure has been initialized and an autotune in progress.
LS	Limit switch active. Indicates that a limit switch is active and that is causing the motor to be stopped.
Lo.AC	Low voltage mode. See <i>Low AC Alarm</i> in <i>Drive User Guide</i> .
I.AC.Lt	Current limit active. See <i>Current Limit Active</i> in <i>Drive User Guide</i> .

9 NV Media Card Operation

Figure 9-1 Installing the AI-Backup adaptor (SD Card)



1. Identify the two plastic fingers on the underside of the AI-Backup adaptor (1) - then insert the two fingers into the corresponding slots in the spring-loaded sliding cover on the top of the drive.
2. Hold the adaptor firmly and push the spring loaded protective cover towards the back of the drive to expose the connector block (2) below.

Press the adaptor downwards (3) until the adaptor connector locates into the drive connection below.

Figure 9-2 Basic NV Media Card operation

<p>Drive reads all parameters from the NV Media Card</p> <p>Pr 00.030 = rEAd + </p>	<p>Programs all drive parameters to the NV Media Card</p> <p>NOTE Overwrites any data already in data block 1</p> <p>Pr 00.030 = Prog + </p>
<p>Drive automatically writes to the Media Card when a parameter save is performed</p> <p>Pr 00.030 = Auto + </p>	<p>Drive boots from the NV Media Card on power up and automatically writes to the Media Card when a parameter save is performed</p> <p>Pr 00.030 = boot + </p>

The whole card may be protected from writing or erasing by setting the read-only flag, refer to the *Drive User Guide* for further information. The card should not be removed during data transfer, as the drive will produce a trip. If this occurs then either the transfer should be reattempted or in the case of a card to drive transfer, default parameters should be loaded.

10 UL listing information

10.1 General

Drive sizes 1 to 4 have been assessed to meet both UL and cUL requirements.

UL listings can be viewed online at www.UL.com. The UL file number is E171230.

10.2 Mounting

Drives can be installed in the following configurations:

- Standard or surface mounted. Refer to the *Drive User Guide* for further information.
- Bookcase mounted. Drives are mounted side by side with no space between them. This configuration minimizes the overall width of the installation.

10.3 Environment

Drives are able to meet the following UL/NEMA environmental ratings:

- Type 1. The drive must either be installed with a UL Type 1 kit or be installed in a Type 1 enclosure.
- Type 12. The drive must be installed in a Type 12 enclosure.
- Drives must be installed in a pollution degree 2 environment or better.

10.4 Electrical ratings

Suitable for use on a circuit capable of delivering not more than 100,000 RMS symmetrical amperes, at the rated maximum AC voltage.

For information on power and current ratings, see the *Drive User Guide*.

Fuse and circuit breaker (size 1 only with short circuit rating of 10 kA) ratings are given in the *Drive User Guide*.

Unless indicated otherwise in the *Drive User Guide*, fuses may be any UL listed Class J or CC with a voltage rating of at least 600 Vac.

Unless indicated otherwise in the *Drive User Guide*, circuit breakers may be any UL listed type, category control number: DIVQ or DIVQ7, with a voltage rating of at least 600 Vac.

10.5 Opening of branch circuit

The opening of the branch-circuit protective device may be an indication that a fault has been interrupted. To reduce the risk of fire or electric shock, the equipment may be examined and replaced if damaged. If burnout of the current element of an overload relay occurs, the complete overload relay must be replaced.

Integral solid state short circuit protection does not provide branch circuit protection. Branch circuit protection must be provided in accordance with the National Electrical Code and any additional local "codes", or the equivalent.

10.6 Electrical installation

The following precautions must be observed:

- Drives are rated for use at 40 °C and 50 °C surrounding air temperature.
- Field wiring terminals are suitable for copper wire only, which must have a temperature rating of at least 75 °C.
- If the drive control stage is powered from an external power supply (+24 V), the power supply must be listed or recognized to UL class 2 with appropriate fusing.
- Ground connections must use UL listed closed loop (ring) terminals.

10.7 cUL requirements for frame size 4

For frame size 4, models Mxxx-042 00133A, Mxxx-042 00176A, Mxxx-044 00135A and Mxxx-044 00170A, transient surge suppression shall be installed on the line side of this equipment and shall be rated 480 Vac (phase to ground), 480 Vac (phase to phase), suitable for overvoltage category III, and shall provide protection for a rated impulse withstand voltage peak of 6 kV and a clamping voltage of maximum 2400 V.

NOTE

Mxxx denotes M100, M101, M200, M201, M300 or M400.

10.8 Motor overload protection

All models incorporate internal overload protection for the motor load that does not require the use of an external or remote overload protection device. The protection level is adjustable and the method of adjustment is provided within instructions/manual for the product. Maximum current overload is dependent on the values entered into the current limit parameters (*Motoring Current Limit* (04.005), *Regenerative Current Limit* (04.006) and *Symmetrical Current Limit* (04.007) entered as percentage) and the *Motor Rated Current* (00.006) entered in amperes). The duration of the overload is dependent on *Motor Thermal Time Constant* (04.015) variable up to a maximum of 3000 seconds. The default overload protection is set such that the product is capable of 150 % of the current value entered into the motor rated current parameter for 60 seconds. The product can be connected to a motor thermistor to protect the motor, in the event of a motor cooling fan failure.

10.9 Motor overspeed protection

The drive is installed with solid state motor overspeed protection.

However, this feature does not provide the level of protection provided by an independent, high-integrity overspeed protection device and should not be considered as a safety function.

10.10 Thermal memory retention

Drives incorporate thermal memory retention that complies fully with the requirements of UL508C.

The drive is provided with motor load and speed sensitive overload protection with thermal memory retention that complies with the US National Electrical Code (NFPA 70) clause 430.126 and Underwriters Laboratories Standard UL508C, clause 20.1.11 (a). The purpose of this protection is to protect both drive and motor from dangerous overheating in the event of repeated overload or failure to start, even if the power to the drive is removed between overload events.

For full explanation of the thermal protection system, refer to the *Drive User Guide* for further information.

In order to comply with UL requirements for thermal memory retention, it is necessary to set the *Thermal Protection Mode* (04.016) to zero; and the *Low Frequency Thermal Protection Mode* (04.025) must be set to 1 if the drive is operated in Heavy Duty mode.

Alternatively, an external thermal sensor or switch may be used as a means of motor and drive overload protection that complies with the requirements of UL508C, clause 20.1.11 (b). This protection method is particularly recommended where independent forced cooling of the motor is used, because of the risk of overheating if the cooling is lost.

External thermal sensor

The drive is provided with a means to accept and act upon a signal from a thermal sensor or switch imbedded in the motor or from an external protective relay. Refer to the *Drive User Guide* for further information.

10.11 Group installation

10.11.1 Definition

Group Installation Definition: A motor branch circuit for two or more motors, or one or more motors with other loads, protected by a circuit breaker or a single set of fuses.

10.11.2 Limitations on use

All motors rated less than 1 hp

The drives may be used in group installations where each of the motors is rated 1 hp or less. The full-load current rating of each motor must not exceed 6 A. The motor drive provides individual overload protection in accordance with the NEC clause 430.32.

Smallest motor protected

The drives may be used in group installations where the smallest motor is protected by the branch fuses or circuit breaker. Limits on the current rating of branch circuit protective fuses and circuit breakers are given in the NEC Table: 430.52.

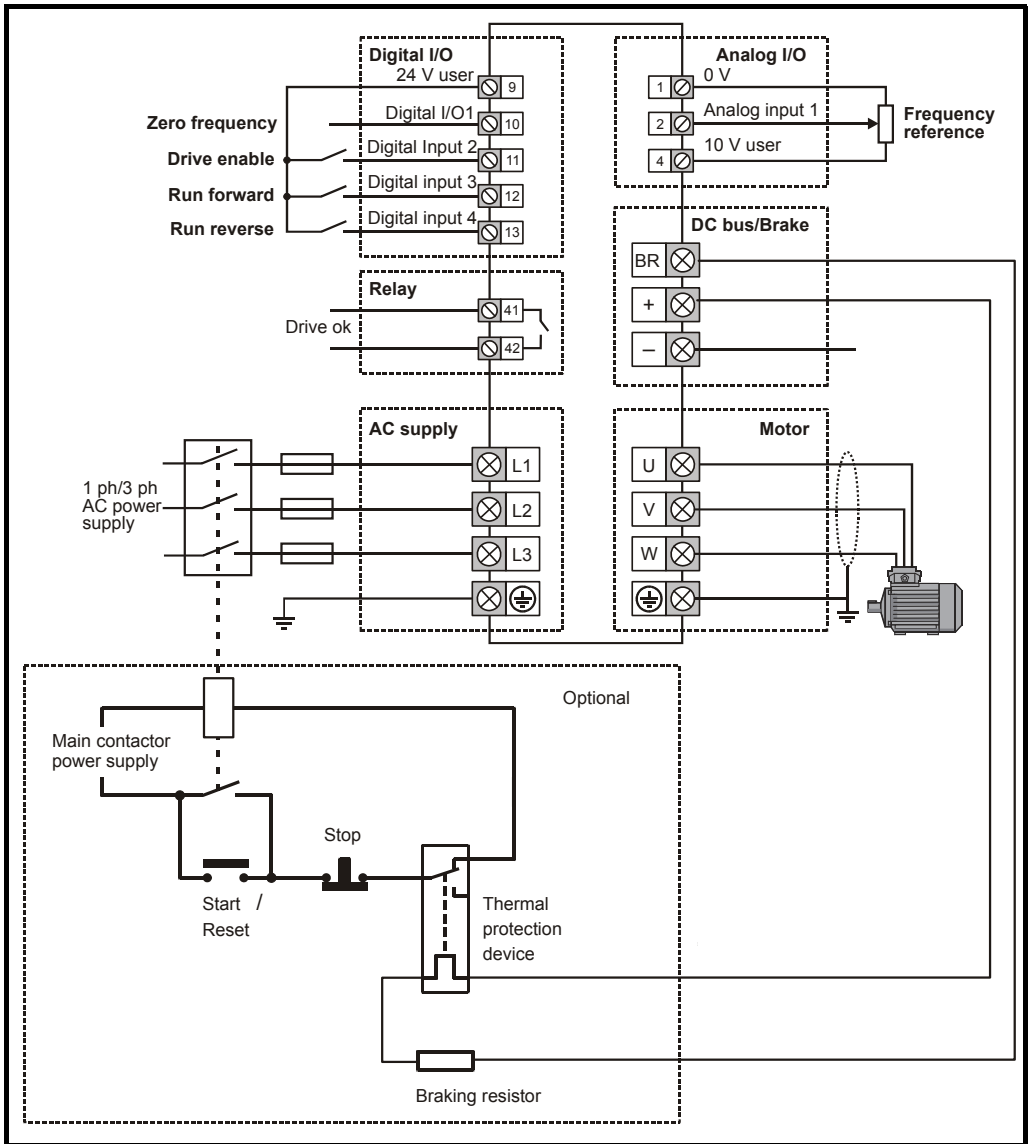
Other installations

The motor drives described in this user guide are not UL listed for group installation.

10.12 UL listed accessories

The following options are UL listed:

- UL Type 1 kit
- NV Media card
- AI-Backup adaptor



NOTE On the size 2 110 V drives or when connecting single phase to a dual rated 200 V unit, the supply should be connected to L1 and L3.



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